

In [1]:

```
%load_ext watermark
%watermark -a 'Sebastian Raschka' -u -d -v -p numpy, scipy, matplotlib
```

UsageError: unrecognized arguments: Raschka'

In [2]:

```
from IPython.display import Image
```

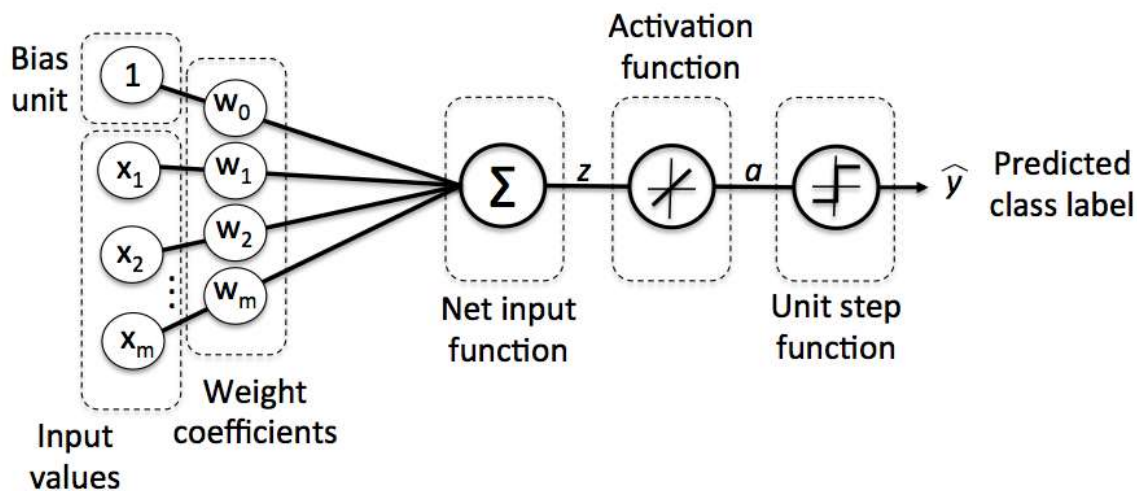
In [3]:

```
%matplotlib inline
```

In [4]:

```
Image(filename='12_01.png', width=600)
```

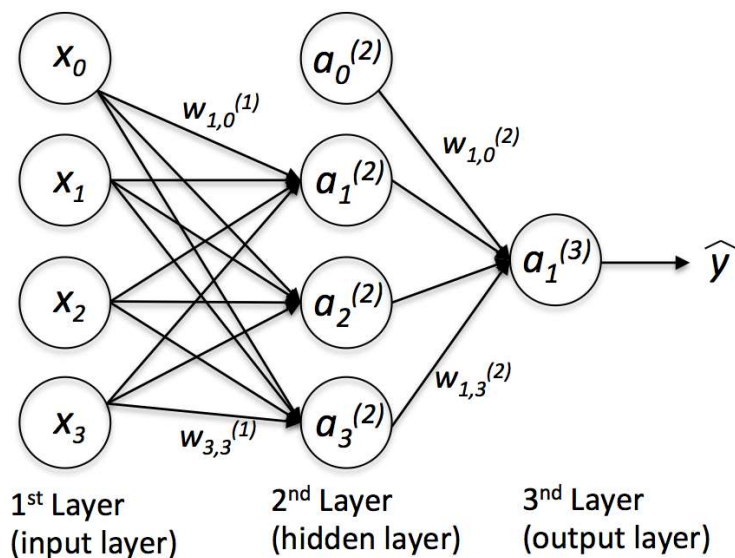
Out[4]:



In [5]:

```
Image(filename='12_02.png', width=400)
```

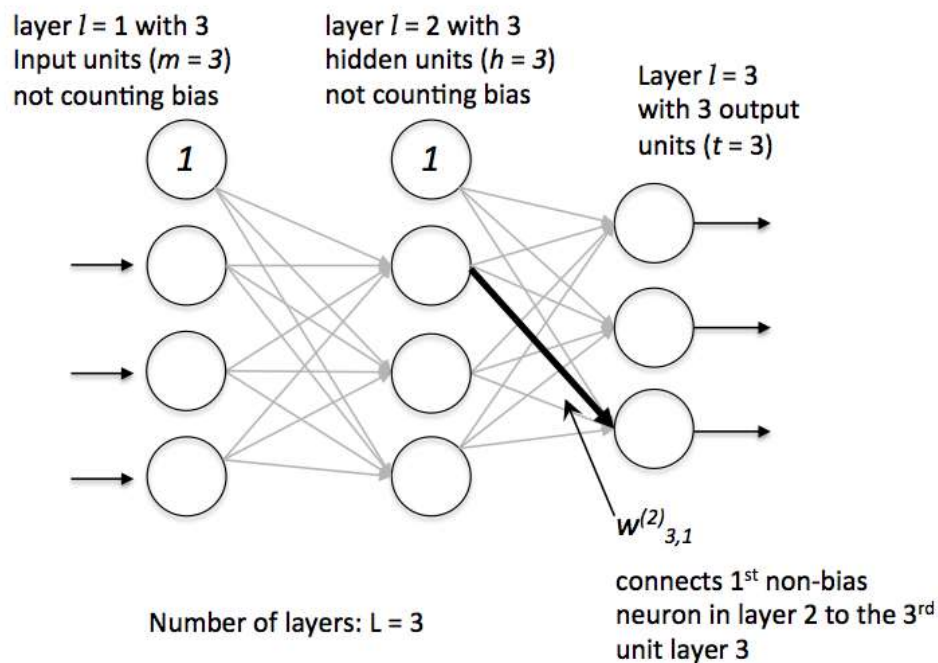
Out[5]:



In [6]:

```
Image(filename='12_03.png', width=500)
```

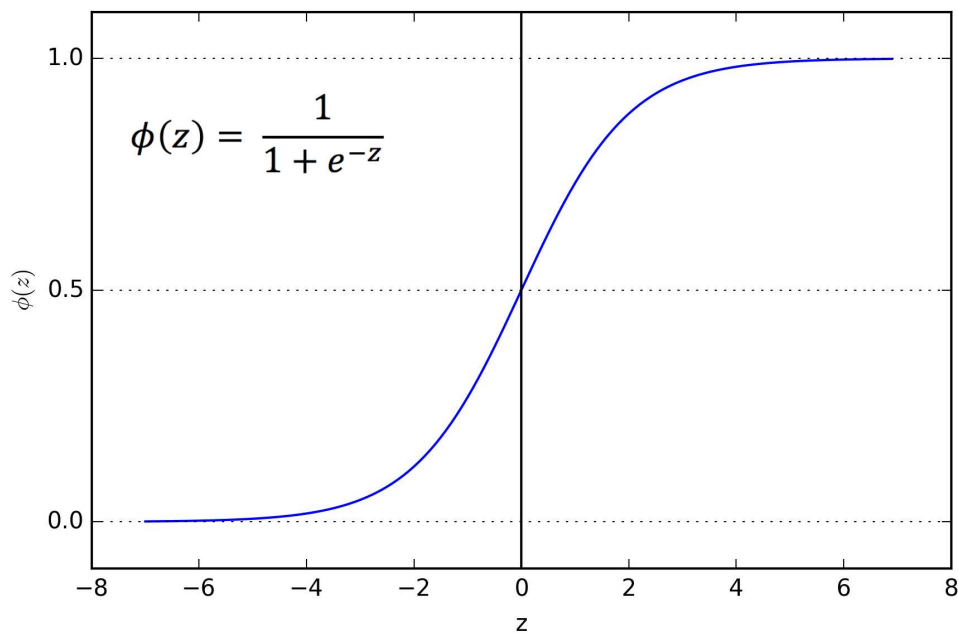
Out[6]:



In [7]:

```
Image(filename='12_04.png', width=500)
```

Out[7]:



In [8]:

```
import os
import struct
import numpy as np

def load_mnist(path, kind='train'):
    """Load MNIST data from `path`"""
    labels_path = os.path.join(path,
                                '%s-labels-idx1-ubyte' % kind)
    images_path = os.path.join(path,
                                '%s-images-idx3-ubyte' % kind)

    with open(labels_path, 'rb') as lpath:
        magic, n = struct.unpack('>II',
                                lpath.read(8))
        labels = np.fromfile(lpath,
                              dtype=np.uint8)

    with open(images_path, 'rb') as imgpath:
        magic, num, rows, cols = struct.unpack(">IIII",
                                                imgpath.read(16))

        images = np.fromfile(imgpath,
                              dtype=np.uint8).reshape(len(labels), 784)

    return images, labels
```

In [9]:

```
X_train, y_train = load_mnist('mnist/', kind='train')
print('Rows: %d, columns: %d' % (X_train.shape[0], X_train.shape[1]))
```

Rows: 60000, columns: 784

In [10]:

```
X_test, y_test = load_mnist('mnist/', kind='t10k')
print('Rows: %d, columns: %d' % (X_test.shape[0], X_test.shape[1]))
```

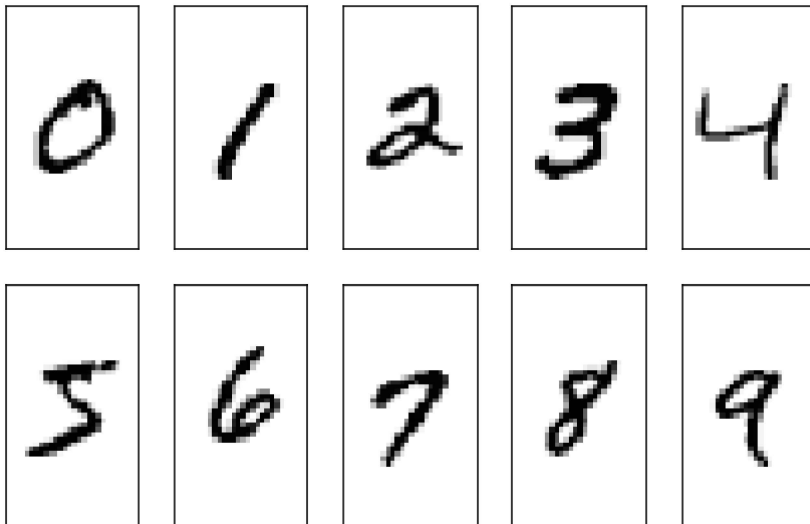
Rows: 10000, columns: 784

In [11]:

```
import matplotlib.pyplot as plt

fig, ax = plt.subplots(nrows=2, ncols=5, sharex=True, sharey=True,)
ax = ax.flatten()
for i in range(10):
    img = X_train[y_train == i][0].reshape(28, 28)
    ax[i].imshow(img, cmap='Greys', interpolation='nearest')

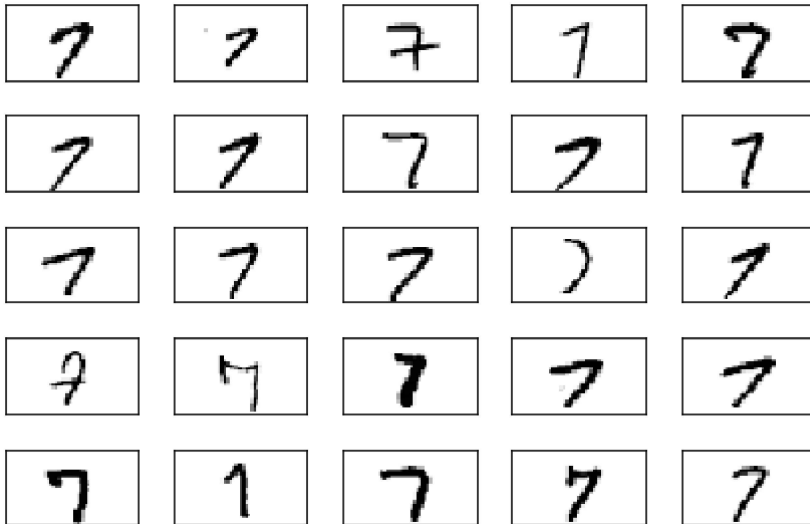
ax[0].set_xticks([])
ax[0].set_yticks([])
plt.tight_layout()
# plt.savefig('./figures/mnist_all.png', dpi=300)
plt.show()
```



In [12]:

```
fig, ax = plt.subplots(nrows=5, ncols=5, sharex=True, sharey=True,)
ax = ax.flatten()
for i in range(25):
    img = X_train[y_train == 7][i].reshape(28, 28)
    ax[i].imshow(img, cmap='Greys', interpolation='nearest')

ax[0].set_xticks([])
ax[0].set_yticks([])
plt.tight_layout()
# plt.savefig('./figures/mnist_7.png', dpi=300)
plt.show()
```



In [13]:

```
# np.savetxt('train_img.csv', X_train, fmt='%i', delimiter=',')
# np.savetxt('train_labels.csv', y_train, fmt='%i', delimiter=',')
# X_train = np.genfromtxt('train_img.csv', dtype=int, delimiter=',')
# y_train = np.genfromtxt('train_labels.csv', dtype=int, delimiter=',')

# np.savetxt('test_img.csv', X_test, fmt='%i', delimiter=',')
# np.savetxt('test_labels.csv', y_test, fmt='%i', delimiter=',')
# X_test = np.genfromtxt('test_img.csv', dtype=int, delimiter=',')
# y_test = np.genfromtxt('test_labels.csv', dtype=int, delimiter=',')
```

In [14]:

```
import numpy as np
from scipy.special import expit
import sys

class NeuralNetMLP(object):
    """ Feedforward neural network / Multi-layer perceptron classifier.

    Parameters
    -----
    n_output : int
        Number of output units, should be equal to the
        number of unique class labels.
    n_features : int
        Number of features (dimensions) in the target dataset.
```

Should be equal to the number of columns in the X array.

n_hidden : int (default: 30)
Number of hidden units.

l1 : float (default: 0.0)
Lambda value for L1-regularization.
No regularization if l1=0.0 (default)

l2 : float (default: 0.0)
Lambda value for L2-regularization.
No regularization if l2=0.0 (default)

epochs : int (default: 500)
Number of passes over the training set.

eta : float (default: 0.001)
Learning rate.

alpha : float (default: 0.0)
Momentum constant. Factor multiplied with the gradient of the previous epoch t-1 to improve learning speed

$$w(t) := w(t) - (\text{grad}(t) + \alpha * \text{grad}(t-1))$$

decrease_const : float (default: 0.0)
*Decrease constant. Shrinks the learning rate after each epoch via $\text{eta} / (1 + \text{epoch} * \text{decrease_const})$*

shuffle : bool (default: True)
Shuffles training data every epoch if True to prevent circles.

minibatches : int (default: 1)
Divides training data into k minibatches for efficiency. Normal gradient descent learning if k=1 (default).

random_state : int (default: None)
Set random state for shuffling and initializing the weights.

Attributes

cost_ : list
Sum of squared errors after each epoch.

"""

```
def __init__(self, n_output, n_features, n_hidden=30,
              l1=0.0, l2=0.0, epochs=500, eta=0.001,
              alpha=0.0, decrease_const=0.0, shuffle=True,
              minibatches=1, random_state=None):
```

```
    np.random.seed(random_state)
    self.n_output = n_output
    self.n_features = n_features
    self.n_hidden = n_hidden
    self.w1, self.w2 = self._initialize_weights()
    self.l1 = l1
    self.l2 = l2
    self.epochs = epochs
    self.eta = eta
    self.alpha = alpha
    self.decrease_const = decrease_const
    self.shuffle = shuffle
    self.minibatches = minibatches
```

```
def _encode_labels(self, y, k):
    """Encode labels into one-hot representation
```

Parameters

y : array, shape = [n_samples]
Target values.

Returns

onehot : array, shape = (n_labels, n_samples)

"""

```
onehot = np.zeros((k, y.shape[0]))
for idx, val in enumerate(y):
    onehot[val, idx] = 1.0
return onehot
```

```
def _initialize_weights(self):
```

"""Initialize weights with small random numbers."""

```
w1 = np.random.uniform(-1.0, 1.0,
                        size=self.n_hidden*(self.n_features + 1))
w1 = w1.reshape(self.n_hidden, self.n_features + 1)
w2 = np.random.uniform(-1.0, 1.0,
                        size=self.n_output*(self.n_hidden + 1))
w2 = w2.reshape(self.n_output, self.n_hidden + 1)
return w1, w2
```

```
def _sigmoid(self, z):
```

"""Compute logistic function (sigmoid)

*Uses scipy.special.expit to avoid overflow
error for very small input values z.*

"""

```
# return 1.0 / (1.0 + np.exp(-z))
return expit(z)
```

```
def _sigmoid_gradient(self, z):
```

"""Compute gradient of the logistic function"""

```
sg = self._sigmoid(z)
return sg * (1.0 - sg)
```

```
def _add_bias_unit(self, X, how='column'):
```

"""Add bias unit (column or row of 1s) to array at index 0"""

```
if how == 'column':
    X_new = np.ones((X.shape[0], X.shape[1] + 1))
    X_new[:, 1:] = X
elif how == 'row':
    X_new = np.ones((X.shape[0] + 1, X.shape[1]))
    X_new[1:, :] = X
else:
    raise AttributeError('`how` must be `column` or `row`')
return X_new
```

```
def _feedforward(self, X, w1, w2):
```

"""Compute feedforward step

Parameters

X : array, shape = [n_samples, n_features]

Input layer with original features.

w1 : array, shape = [n_hidden_units, n_features]

Weight matrix for input layer → hidden layer.

w2 : array, shape = [n_output_units, n_hidden_units]

Weight matrix for hidden layer → output layer.

Returns

```

-----
a1 : array, shape = [n_samples, n_features+1]
      Input values with bias unit.
z2 : array, shape = [n_hidden, n_samples]
      Net input of hidden layer.
a2 : array, shape = [n_hidden+1, n_samples]
      Activation of hidden layer.
z3 : array, shape = [n_output_units, n_samples]
      Net input of output layer.
a3 : array, shape = [n_output_units, n_samples]
      Activation of output layer.

"""

a1 = self._add_bias_unit(X, how='column')
z2 = w1.dot(a1.T)
a2 = self._sigmoid(z2)
a2 = self._add_bias_unit(a2, how='row')
z3 = w2.dot(a2)
a3 = self._sigmoid(z3)
return a1, z2, a2, z3, a3

def _L2_reg(self, lambda_, w1, w2):
    """Compute L2-regularization cost"""
    return (lambda_/2.0) * (np.sum(w1[:, 1:] ** 2) +
                             np.sum(w2[:, 1:] ** 2))

def _L1_reg(self, lambda_, w1, w2):
    """Compute L1-regularization cost"""
    return (lambda_/2.0) * (np.abs(w1[:, 1:]).sum() +
                             np.abs(w2[:, 1:]).sum())

def _get_cost(self, y_enc, output, w1, w2):
    """Compute cost function.

    Parameters
    -----
    y_enc : array, shape = (n_labels, n_samples)
            one-hot encoded class labels.
    output : array, shape = [n_output_units, n_samples]
            Activation of the output layer (feedforward)
    w1 : array, shape = [n_hidden_units, n_features]
         Weight matrix for input layer -> hidden layer.
    w2 : array, shape = [n_output_units, n_hidden_units]
         Weight matrix for hidden layer -> output layer.

    Returns
    -----
    cost : float
           Regularized cost.

    """
    term1 = -y_enc * (np.log(output))
    term2 = (1.0 - y_enc) * np.log(1.0 - output)
    cost = np.sum(term1 - term2)
    L1_term = self._L1_reg(self.l1, w1, w2)
    L2_term = self._L2_reg(self.l2, w1, w2)
    cost = cost + L1_term + L2_term
    return cost

def _get_gradient(self, a1, a2, a3, z2, y_enc, w1, w2):
    """ Compute gradient step using backpropagation.

```

Parameters

```

a1 : array, shape = [n_samples, n_features+1]
    Input values with bias unit.
a2 : array, shape = [n_hidden+1, n_samples]
    Activation of hidden layer.
a3 : array, shape = [n_output_units, n_samples]
    Activation of output layer.
z2 : array, shape = [n_hidden, n_samples]
    Net input of hidden layer.
y_enc : array, shape = (n_labels, n_samples)
    one-hot encoded class labels.
w1 : array, shape = [n_hidden_units, n_features]
    Weight matrix for input layer -> hidden layer.
w2 : array, shape = [n_output_units, n_hidden_units]
    Weight matrix for hidden layer -> output layer.

```

Returns

```

grad1 : array, shape = [n_hidden_units, n_features]
    Gradient of the weight matrix w1.
grad2 : array, shape = [n_output_units, n_hidden_units]
    Gradient of the weight matrix w2.

```

```

"""

```

```

# backpropagation
sigma3 = a3 - y_enc
z2 = self._add_bias_unit(z2, how='row')
sigma2 = w2.T.dot(sigma3) * self._sigmoid_gradient(z2)
sigma2 = sigma2[1:, :]
grad1 = sigma2.dot(a1)
grad2 = sigma3.dot(a2.T)

```

```

# regularize
grad1[:, 1:] += (w1[:, 1:] * (self.l1 + self.l2))
grad2[:, 1:] += (w2[:, 1:] * (self.l1 + self.l2))

```

```

return grad1, grad2

```

```

def predict(self, X):
    """Predict class labels

```

Parameters

```

X : array, shape = [n_samples, n_features]
    Input layer with original features.

```

Returns:

```

y_pred : array, shape = [n_samples]
    Predicted class labels.

```

```

"""

```

```

if len(X.shape) != 2:
    raise AttributeError('X must be a [n_samples, n_features] array.%n'
                        'Use X[:,None] for 1-feature classification,'
                        '%nX[[i]] for 1-sample classification')

```

```

a1, z2, a2, z3, a3 = self._feedforward(X, self.w1, self.w2)
y_pred = np.argmax(z3, axis=0)

```

```

return y_pred

def fit(self, X, y, print_progress=False):
    """ Learn weights from training data.

    Parameters
    -----
    X : array, shape = [n_samples, n_features]
        Input layer with original features.
    y : array, shape = [n_samples]
        Target class labels.
    print_progress : bool (default: False)
        Prints progress as the number of epochs
        to stderr.

    Returns:
    -----
    self
    """
    self.cost_ = []
    X_data, y_data = X.copy(), y.copy()
    y_enc = self._encode_labels(y, self.n_output)

    delta_w1_prev = np.zeros(self.w1.shape)
    delta_w2_prev = np.zeros(self.w2.shape)

    for i in range(self.epochs):

        # adaptive learning rate
        self.eta /= (1 + self.decrease_const*i)

        if print_progress:
            sys.stderr.write('¥rEpoch: %d/%d' % (i+1, self.epochs))
            sys.stderr.flush()

        if self.shuffle:
            idx = np.random.permutation(y_data.shape[0])
            X_data, y_enc = X_data[idx], y_enc[:, idx]

        mini = np.array_split(range(y_data.shape[0]), self.minibatches)
        for idx in mini:

            # feedforward
            a1, z2, a2, z3, a3 = self._feedforward(X_data[idx],
                                                    self.w1,
                                                    self.w2)
            cost = self._get_cost(y_enc=y_enc[:, idx],
                                  output=a3,
                                  w1=self.w1,
                                  w2=self.w2)
            self.cost_.append(cost)

            # compute gradient via backpropagation
            grad1, grad2 = self._get_gradient(a1=a1, a2=a2,
                                              a3=a3, z2=z2,
                                              y_enc=y_enc[:, idx],
                                              w1=self.w1,
                                              w2=self.w2)

            delta_w1, delta_w2 = self.eta * grad1, self.eta * grad2

```

```

self.w1 -= (delta_w1 + (self.alpha * delta_w1_prev))
self.w2 -= (delta_w2 + (self.alpha * delta_w2_prev))
delta_w1_prev, delta_w2_prev = delta_w1, delta_w2

```

```

return self

```

In [15]:

```

nn = NeuralNetMLP(n_output=10,
                  n_features=X_train.shape[1],
                  n_hidden=50,
                  l2=0.1,
                  l1=0.0,
                  epochs=1000,
                  eta=0.001,
                  alpha=0.001,
                  decrease_const=0.00001,
                  minibatches=50,
                  shuffle=True,
                  random_state=1)

```

In [16]:

```

nn.fit(X_train, y_train, print_progress=True)

```

Epoch: 1000/1000

Out[16]:

<__main__.NeuralNetMLP at 0x18af0e11198>

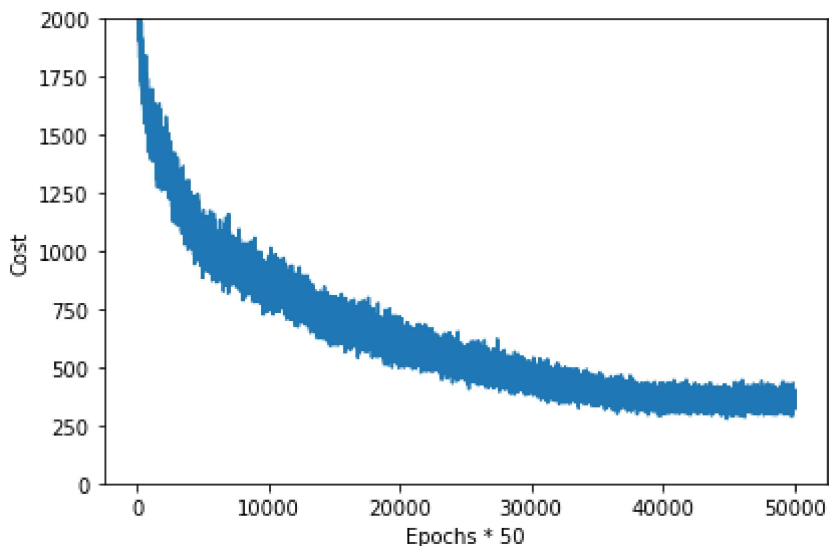
In [17]:

```

import matplotlib.pyplot as plt

plt.plot(range(len(nn.cost_)), nn.cost_)
plt.ylim([0, 2000])
plt.ylabel('Cost')
plt.xlabel('Epochs * 50')
plt.tight_layout()
# plt.savefig('./figures/cost.png', dpi=300)
plt.show()

```

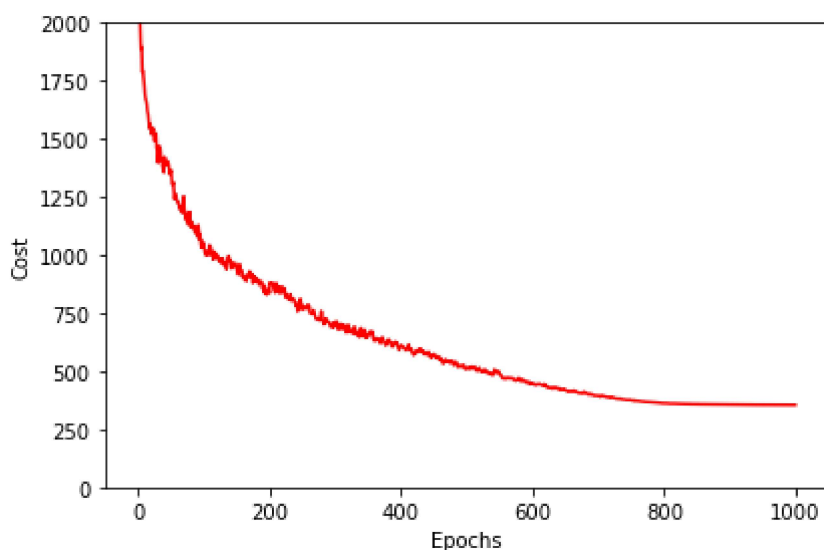


In [18]:

```
batches = np.array_split(range(len(nn.cost_)), 1000)
cost_ary = np.array(nn.cost_)
cost_avgs = [np.mean(cost_ary[i]) for i in batches]
```

In [19]:

```
plt.plot(range(len(cost_avgs)), cost_avgs, color='red')
plt.ylim([0, 2000])
plt.ylabel('Cost')
plt.xlabel('Epochs')
plt.tight_layout()
#plt.savefig('./figures/cost2.png', dpi=300)
plt.show()
```



In [20]:

```
y_train_pred = nn.predict(X_train)

if sys.version_info < (3, 0):
    acc = ((np.sum(y_train == y_train_pred, axis=0)).astype('float') /
           X_train.shape[0])
else:
    acc = np.sum(y_train == y_train_pred, axis=0) / X_train.shape[0]

print('Training accuracy: %.2f%%' % (acc * 100))
```

Training accuracy: 97.69%

In [21]:

```
y_test_pred = nn.predict(X_test)

if sys.version_info < (3, 0):
    acc = ((np.sum(y_test == y_test_pred, axis=0)).astype('float') /
           X_test.shape[0])
else:
    acc = np.sum(y_test == y_test_pred, axis=0) / X_test.shape[0]

print('Test accuracy: %.2f%%' % (acc * 100))
```

Test accuracy: 95.79%

In [22]:

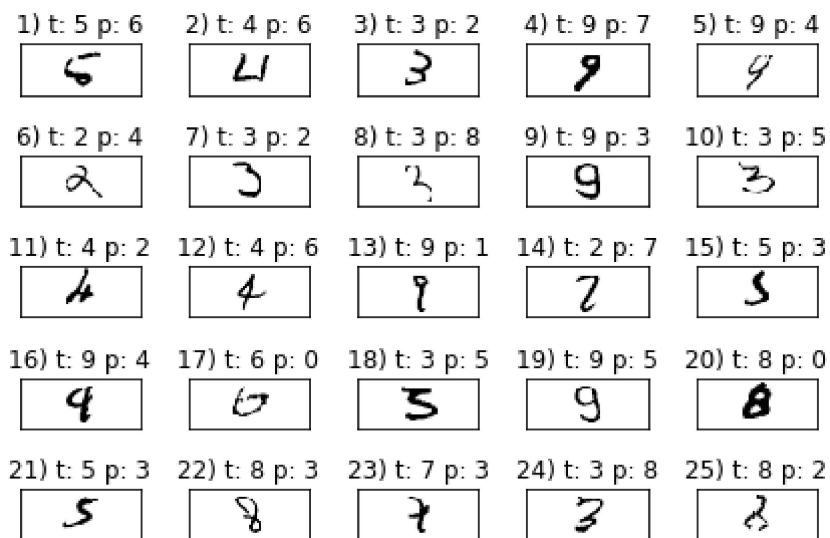
```

misc_img = X_test[y_test != y_test_pred][:25]
correct_lab = y_test[y_test != y_test_pred][:25]
misc_lab = y_test_pred[y_test != y_test_pred][:25]

fig, ax = plt.subplots(nrows=5, ncols=5, sharex=True, sharey=True,)
ax = ax.flatten()
for i in range(25):
    img = misc_img[i].reshape(28, 28)
    ax[i].imshow(img, cmap='Greys', interpolation='nearest')
    ax[i].set_title('%d t: %d p: %d' % (i+1, correct_lab[i], misc_lab[i]))

ax[0].set_xticks([])
ax[0].set_yticks([])
plt.tight_layout()
# plt.savefig('./figures/mnist_misl.png', dpi=300)
plt.show()

```



In [23]:

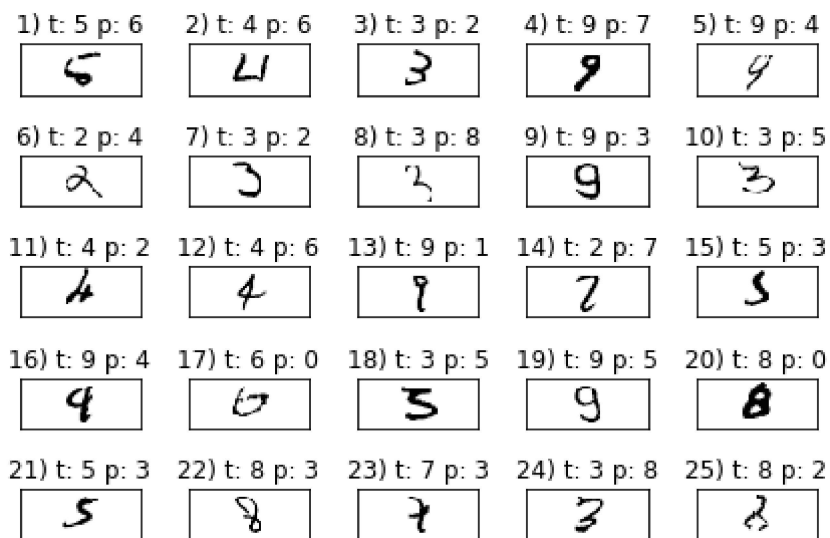
```

misc1_img = X_test[y_test != y_test_pred][:25]
correct_lab = y_test[y_test != y_test_pred][:25]
misc1_lab= y_test_pred[y_test != y_test_pred][:25]

fig, ax = plt.subplots(nrows=5, ncols=5, sharex=True, sharey=True,)
ax = ax.flatten()
for i in range(25):
    img = misc1_img[i].reshape(28, 28)
    ax[i].imshow(img, cmap='Greys', interpolation='nearest')
    ax[i].set_title('%d t: %d p: %d' % (i+1, correct_lab[i], misc1_lab[i]))

ax[0].set_xticks([])
ax[0].set_yticks([])
plt.tight_layout()
# plt.savefig('./figures/mnist_misc1.png', dpi=300)
plt.show()

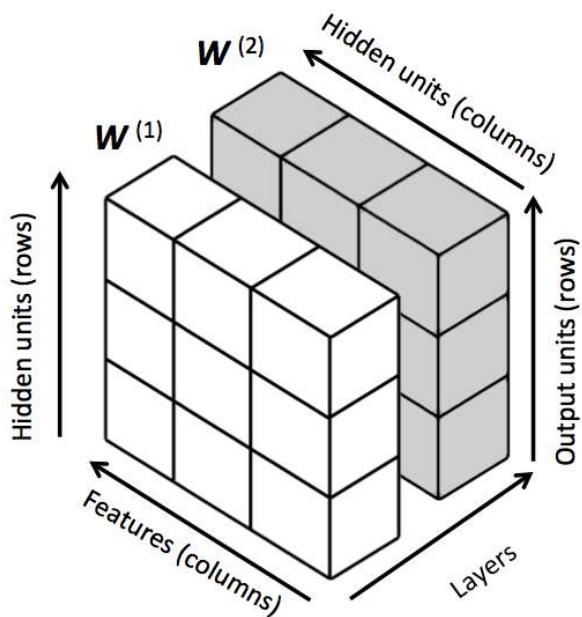
```



In [24]:

```
Image(filename='12_10.png', width=300)
```

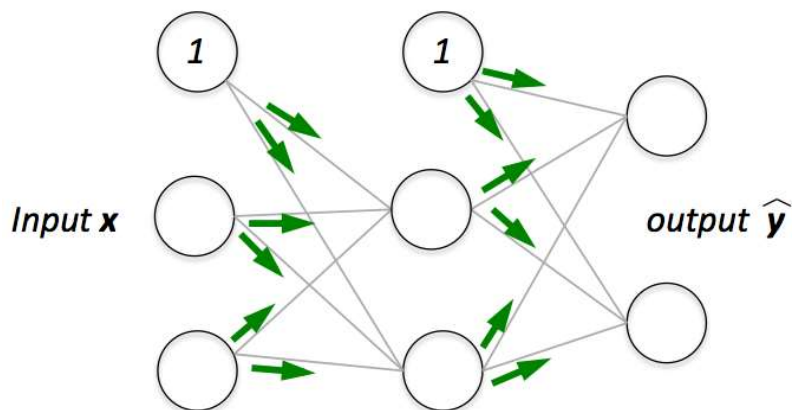
Out[24]:



In [25]:

```
Image(filename='12_11.png', width=400)
```

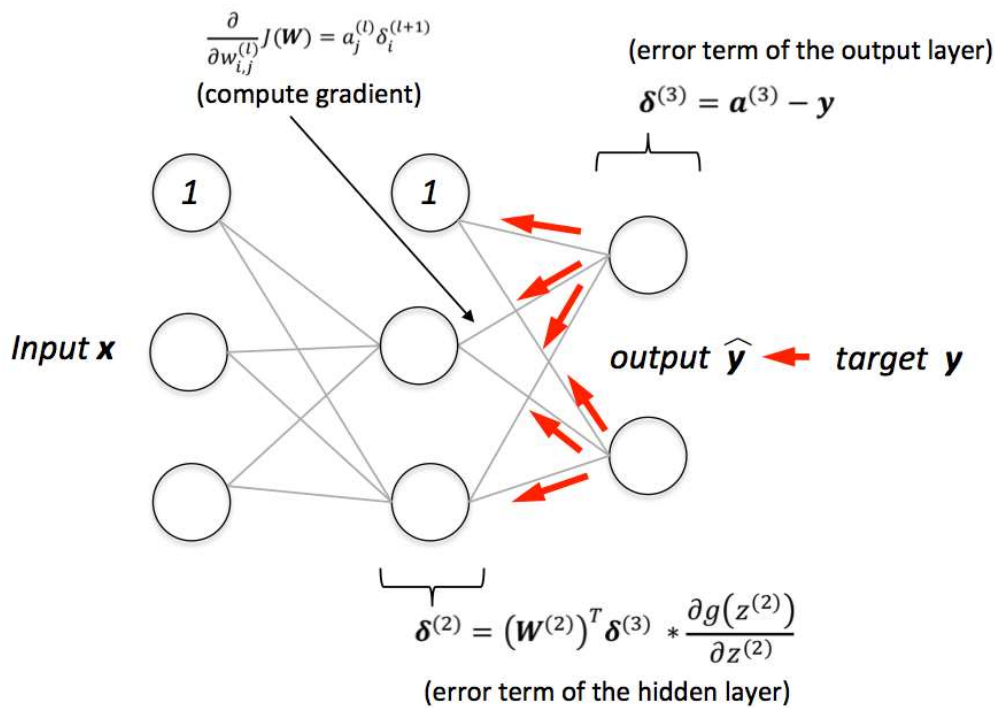
Out[25]:



In [26]:

```
Image(filename='12_12.png', width=500)
```

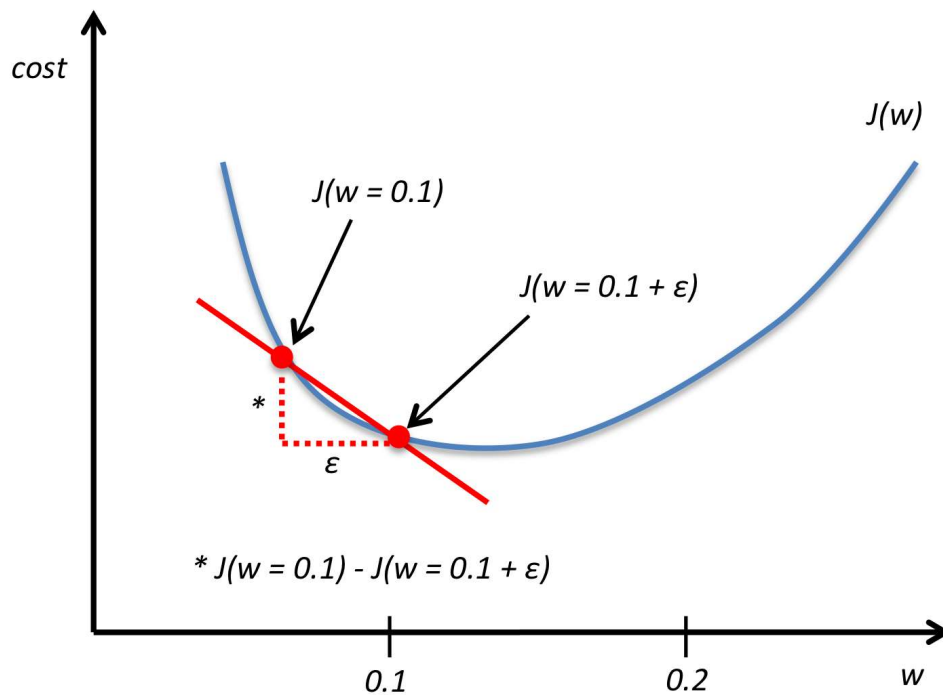
Out[26]:



In [27]:

```
Image(filename='12_13.png', width=500)
```

Out[27]:



In [28]:

```
from scipy import __version__ as scipy_ver
from numpy import __version__ as numpy_ver

print('The following code requires NumPy >= 1.9.1. Your NumPy version is %s.' % (numpy_ver))
print('The following code requires SciPy >= 0.14.0. Your SciPy version is %s.' % (scipy_ver))
```

The following code requires NumPy >= 1.9.1. Your NumPy version is 1.12.1.
The following code requires SciPy >= 0.14.0. Your SciPy version is 0.19.0.

In [29]:

```
import numpy as np
from scipy.special import expit
import sys

class MLPGradientCheck(object):
    """ Feedforward neural network / Multi-layer perceptron classifier.

    Parameters
    -----
    n_output : int
        Number of output units, should be equal to the
        number of unique class labels.
    n_features : int
        Number of features (dimensions) in the target dataset.
        Should be equal to the number of columns in the X array.
    n_hidden : int (default: 30)
        Number of hidden units.
    l1 : float (default: 0.0)
        Lambda value for L1-regularization.
        No regularization if l1=0.0 (default)
    l2 : float (default: 0.0)
        Lambda value for L2-regularization.
        No regularization if l2=0.0 (default)
    epochs : int (default: 500)
        Number of passes over the training set.
    eta : float (default: 0.001)
        Learning rate.
    alpha : float (default: 0.0)
        Momentum constant. Factor multiplied with the
        gradient of the previous epoch t-1 to improve
        learning speed
         $w(t) := w(t) - (\text{grad}(t) + \alpha * \text{grad}(t-1))$ 
    decrease_const : float (default: 0.0)
        Decrease constant. Shrinks the learning rate
        after each epoch via  $\text{eta} / (1 + \text{epoch} * \text{decrease\_const})$ 
    shuffle : bool (default: False)
        Shuffles training data every epoch if True to prevent circles.
    minibatches : int (default: 1)
        Divides training data into k minibatches for efficiency.
        Normal gradient descent learning if k=1 (default).
    random_state : int (default: None)
        Set random state for shuffling and initializing the weights.

    Attributes
    -----
    cost_ : list
        Sum of squared errors after each epoch.
```

```

"""
def __init__(self, n_output, n_features, n_hidden=30,
              l1=0.0, l2=0.0, epochs=500, eta=0.001,
              alpha=0.0, decrease_const=0.0, shuffle=True,
              minibatches=1, random_state=None):

    np.random.seed(random_state)
    self.n_output = n_output
    self.n_features = n_features
    self.n_hidden = n_hidden
    self.w1, self.w2 = self._initialize_weights()
    self.l1 = l1
    self.l2 = l2
    self.epochs = epochs
    self.eta = eta
    self.alpha = alpha
    self.decrease_const = decrease_const
    self.shuffle = shuffle
    self.minibatches = minibatches

def _encode_labels(self, y, k):
    """Encode labels into one-hot representation

    Parameters
    -----
    y : array, shape = [n_samples]
        Target values.

    Returns
    -----
    onehot : array, shape = (n_labels, n_samples)

    """
    onehot = np.zeros((k, y.shape[0]))
    for idx, val in enumerate(y):
        onehot[val, idx] = 1.0
    return onehot

def _initialize_weights(self):
    """Initialize weights with small random numbers. """
    w1 = np.random.uniform(-1.0, 1.0,
                           size=self.n_hidden*(self.n_features + 1))
    w1 = w1.reshape(self.n_hidden, self.n_features + 1)
    w2 = np.random.uniform(-1.0, 1.0,
                           size=self.n_output*(self.n_hidden + 1))
    w2 = w2.reshape(self.n_output, self.n_hidden + 1)
    return w1, w2

def _sigmoid(self, z):
    """Compute logistic function (sigmoid)

    Uses scipy.special.expit to avoid overflow
    error for very small input values z.

    """
    # return 1.0 / (1.0 + np.exp(-z))
    return expit(z)

def _sigmoid_gradient(self, z):
    """Compute gradient of the logistic function"""

```

```

sg = self._sigmoid(z)
return sg * (1.0 - sg)

def _add_bias_unit(self, X, how='column'):
    """Add bias unit (column or row of 1s) to array at index 0"""
    if how == 'column':
        X_new = np.ones((X.shape[0], X.shape[1] + 1))
        X_new[:, 1:] = X
    elif how == 'row':
        X_new = np.ones((X.shape[0]+1, X.shape[1]))
        X_new[1:, :] = X
    else:
        raise AttributeError('`how` must be `column` or `row`')
    return X_new

def _feedforward(self, X, w1, w2):
    """Compute feedforward step

    Parameters
    -----
    X : array, shape = [n_samples, n_features]
        Input layer with original features.
    w1 : array, shape = [n_hidden_units, n_features]
        Weight matrix for input layer -> hidden layer.
    w2 : array, shape = [n_output_units, n_hidden_units]
        Weight matrix for hidden layer -> output layer.

    Returns
    -----
    a1 : array, shape = [n_samples, n_features+1]
        Input values with bias unit.
    z2 : array, shape = [n_hidden, n_samples]
        Net input of hidden layer.
    a2 : array, shape = [n_hidden+1, n_samples]
        Activation of hidden layer.
    z3 : array, shape = [n_output_units, n_samples]
        Net input of output layer.
    a3 : array, shape = [n_output_units, n_samples]
        Activation of output layer.

    """
    a1 = self._add_bias_unit(X, how='column')
    z2 = w1.dot(a1.T)
    a2 = self._sigmoid(z2)
    a2 = self._add_bias_unit(a2, how='row')
    z3 = w2.dot(a2)
    a3 = self._sigmoid(z3)
    return a1, z2, a2, z3, a3

def _L2_reg(self, lambda_, w1, w2):
    """Compute L2-regularization cost"""
    return (lambda_/2.0) * (np.sum(w1[:, 1:] ** 2) +
                             np.sum(w2[:, 1:] ** 2))

def _L1_reg(self, lambda_, w1, w2):
    """Compute L1-regularization cost"""
    return (lambda_/2.0) * (np.abs(w1[:, 1:]).sum() +
                             np.abs(w2[:, 1:]).sum())

def _get_cost(self, y_enc, output, w1, w2):
    """Compute cost function.

```

Parameters

```

y_enc : array, shape = (n_labels, n_samples)
        one-hot encoded class labels.
output : array, shape = [n_output_units, n_samples]
        Activation of the output layer (feedforward)
w1 : array, shape = [n_hidden_units, n_features]
        Weight matrix for input layer -> hidden layer.
w2 : array, shape = [n_output_units, n_hidden_units]
        Weight matrix for hidden layer -> output layer.

```

Returns

```

cost : float
        Regularized cost.

```

```

"""

```

```

term1 = -y_enc * (np.log(output))
term2 = (1.0 - y_enc) * np.log(1.0 - output)
cost = np.sum(term1 - term2)
L1_term = self._L1_reg(self.l1, w1, w2)
L2_term = self._L2_reg(self.l2, w1, w2)
cost = cost + L1_term + L2_term
return cost

```

```

def _get_gradient(self, a1, a2, a3, z2, y_enc, w1, w2):
    """ Compute gradient step using backpropagation.

```

Parameters

```

a1 : array, shape = [n_samples, n_features+1]
        Input values with bias unit.
a2 : array, shape = [n_hidden+1, n_samples]
        Activation of hidden layer.
a3 : array, shape = [n_output_units, n_samples]
        Activation of output layer.
z2 : array, shape = [n_hidden, n_samples]
        Net input of hidden layer.
y_enc : array, shape = (n_labels, n_samples)
        one-hot encoded class labels.
w1 : array, shape = [n_hidden_units, n_features]
        Weight matrix for input layer -> hidden layer.
w2 : array, shape = [n_output_units, n_hidden_units]
        Weight matrix for hidden layer -> output layer.

```

Returns

```

grad1 : array, shape = [n_hidden_units, n_features]
        Gradient of the weight matrix w1.
grad2 : array, shape = [n_output_units, n_hidden_units]
        Gradient of the weight matrix w2.

```

```

"""

```

```

# backpropagation
sigma3 = a3 - y_enc
z2 = self._add_bias_unit(z2, how='row')
sigma2 = w2.T.dot(sigma3) * self._sigmoid_gradient(z2)
sigma2 = sigma2[1:, :]
grad1 = sigma2.dot(a1)
grad2 = sigma3.dot(a2.T)

```

```

# regularize
grad1[:, 1:] += (w1[:, 1:] * (self.l1 + self.l2))
grad2[:, 1:] += (w2[:, 1:] * (self.l1 + self.l2))

return grad1, grad2

def _gradient_checking(self, X, y_enc, w1, w2, epsilon, grad1, grad2):
    """ Apply gradient checking (for debugging only)

    Returns
    -----
    relative_error : float
        Relative error between the numerically
        approximated gradients and the backpropagated gradients.

    """
    num_grad1 = np.zeros(np.shape(w1))
    epsilon_ary1 = np.zeros(np.shape(w1))
    for i in range(w1.shape[0]):
        for j in range(w1.shape[1]):
            epsilon_ary1[i, j] = epsilon
            a1, z2, a2, z3, a3 = self._feedforward(X,
                                                    w1 - epsilon_ary1, w2)
            cost1 = self._get_cost(y_enc, a3, w1 - epsilon_ary1, w2)
            a1, z2, a2, z3, a3 = self._feedforward(X,
                                                    w1 + epsilon_ary1, w2)
            cost2 = self._get_cost(y_enc, a3, w1 + epsilon_ary1, w2)
            num_grad1[i, j] = (cost2 - cost1) / (2.0 * epsilon)
            epsilon_ary1[i, j] = 0

    num_grad2 = np.zeros(np.shape(w2))
    epsilon_ary2 = np.zeros(np.shape(w2))
    for i in range(w2.shape[0]):
        for j in range(w2.shape[1]):
            epsilon_ary2[i, j] = epsilon
            a1, z2, a2, z3, a3 = self._feedforward(X, w1,
                                                    w2 - epsilon_ary2)
            cost1 = self._get_cost(y_enc, a3, w1, w2 - epsilon_ary2)
            a1, z2, a2, z3, a3 = self._feedforward(X, w1,
                                                    w2 + epsilon_ary2)
            cost2 = self._get_cost(y_enc, a3, w1, w2 + epsilon_ary2)
            num_grad2[i, j] = (cost2 - cost1) / (2.0 * epsilon)
            epsilon_ary2[i, j] = 0

    num_grad = np.hstack((num_grad1.flatten(), num_grad2.flatten()))
    grad = np.hstack((grad1.flatten(), grad2.flatten()))
    norm1 = np.linalg.norm(num_grad - grad)
    norm2 = np.linalg.norm(num_grad)
    norm3 = np.linalg.norm(grad)
    relative_error = norm1 / (norm2 + norm3)
    return relative_error

def predict(self, X):
    """Predict class labels

    Parameters
    -----
    X : array, shape = [n_samples, n_features]
        Input layer with original features.

```

Returns:

y_pred : array, shape = [n_samples]
Predicted class labels.

"""

```
if len(X.shape) != 2:
    raise AttributeError('X must be a [n_samples, n_features] array.¥n'
                        'Use X[:,None] for 1-feature classification,'
                        '¥nor X[[i]] for 1-sample classification')
```

```
a1, z2, a2, z3, a3 = self._feedforward(X, self.w1, self.w2)
y_pred = np.argmax(z3, axis=0)
return y_pred
```

```
def fit(self, X, y, print_progress=False):
    """ Learn weights from training data.
```

Parameters

X : array, shape = [n_samples, n_features]
Input layer with original features.
y : array, shape = [n_samples]
Target class labels.
print_progress : bool (default: False)
Prints progress as the number of epochs
to stderr.

Returns:

self

"""

```
self.cost_ = []
X_data, y_data = X.copy(), y.copy()
y_enc = self._encode_labels(y, self.n_output)
```

```
delta_w1_prev = np.zeros(self.w1.shape)
delta_w2_prev = np.zeros(self.w2.shape)
```

```
for i in range(self.epochs):
```

```
    # adaptive learning rate
    self.eta /= (1 + self.decrease_const*i)
```

```
    if print_progress:
        sys.stderr.write('¥rEpoch: %d/%d' % (i+1, self.epochs))
        sys.stderr.flush()
```

```
    if self.shuffle:
        idx = np.random.permutation(y_data.shape[0])
        X_data, y_enc = X_data[idx], y_enc[idx]
```

```
    mini = np.array_split(range(y_data.shape[0]), self.minibatches)
    for idx in mini:
```

```
        # feedforward
        a1, z2, a2, z3, a3 = self._feedforward(X[idx],
                                                self.w1,
                                                self.w2)

        cost = self._get_cost(y_enc=y_enc[:, idx],
```

```

        output=a3,
        w1=self.w1,
        w2=self.w2)
self.cost_.append(cost)

# compute gradient via backpropagation
grad1, grad2 = self._get_gradient(a1=a1, a2=a2,
                                   a3=a3, z2=z2,
                                   y_enc=y_enc[:, idx],
                                   w1=self.w1,
                                   w2=self.w2)

# start gradient checking
grad_diff = self._gradient_checking(X=X_data[idx],
                                     y_enc=y_enc[:, idx],
                                     w1=self.w1,
                                     w2=self.w2,
                                     epsilon=1e-5,
                                     grad1=grad1,
                                     grad2=grad2)

if grad_diff <= 1e-7:
    print('Ok: %s' % grad_diff)
elif grad_diff <= 1e-4:
    print('Warning: %s' % grad_diff)
else:
    print('PROBLEM: %s' % grad_diff)

# update weights: [alpha * delta_w_prev] for momentum learning
delta_w1, delta_w2 = self.eta * grad1, self.eta * grad2
self.w1 -= (delta_w1 + (self.alpha * delta_w1_prev))
self.w2 -= (delta_w2 + (self.alpha * delta_w2_prev))
delta_w1_prev, delta_w2_prev = delta_w1, delta_w2

return self

```

In [30]:

```

nn_check = MLPGradientCheck(n_output=10,
                             n_features=X_train.shape[1],
                             n_hidden=10,
                             l2=0.0,
                             l1=0.0,
                             epochs=10,
                             eta=0.001,
                             alpha=0.0,
                             decrease_const=0.0,
                             minibatches=1,
                             shuffle=False,
                             random_state=1)

```